

Red Hat
Summit

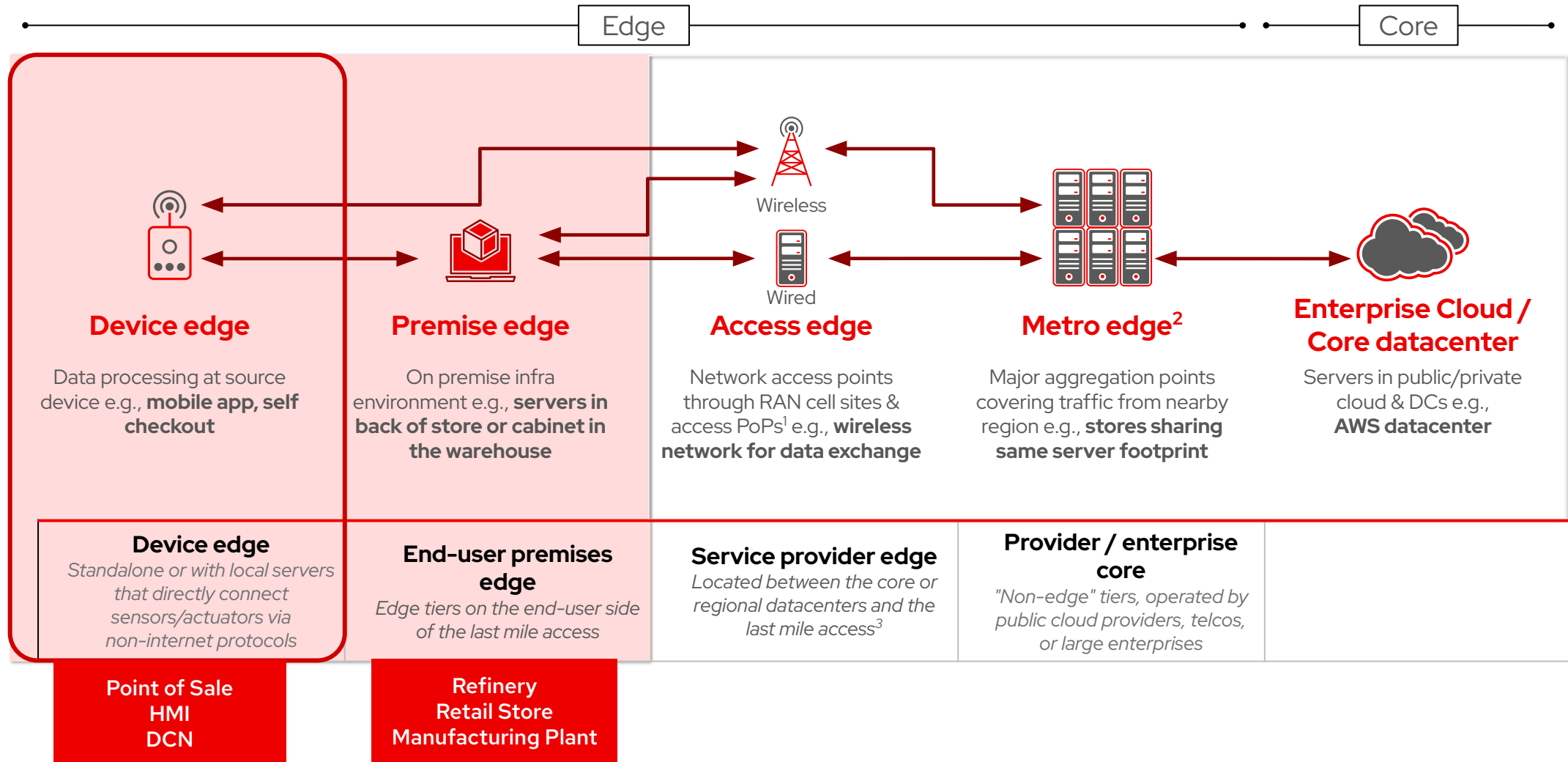
Red Hat Device Edge Deep Dive

Agenda

- ▶ Red Hat's Approach to Edge
- ▶ What is Red Hat Device Edge?
- ▶ Overview of Image Builder + Demo
- ▶ Deploying a Composed Image
- ▶ Configuring Greenboot + Demo
- ▶ Building Applications into Images + Demo
- ▶ Deploying Microshift + Demo

Red Hat's Approach to Edge

So what and where is the edge?



1. Fixed network access equipment that connects from on premise to large aggregation centers; 2. Inclusive of potentially multiple layers of network including ISP data centers, edge data centers, etc.; 3. Commonly owned and operated by a telco or internet service provider and from which this provider serves multiple customers; 4. Mostly enterprise-grade
Source: BCG analysis

Retail Store Architecture

Back of Store (Site Premise)

- AAP: network automation
- RHDE management
- ODF: data aggregation
- Virtualization: legacy workloads

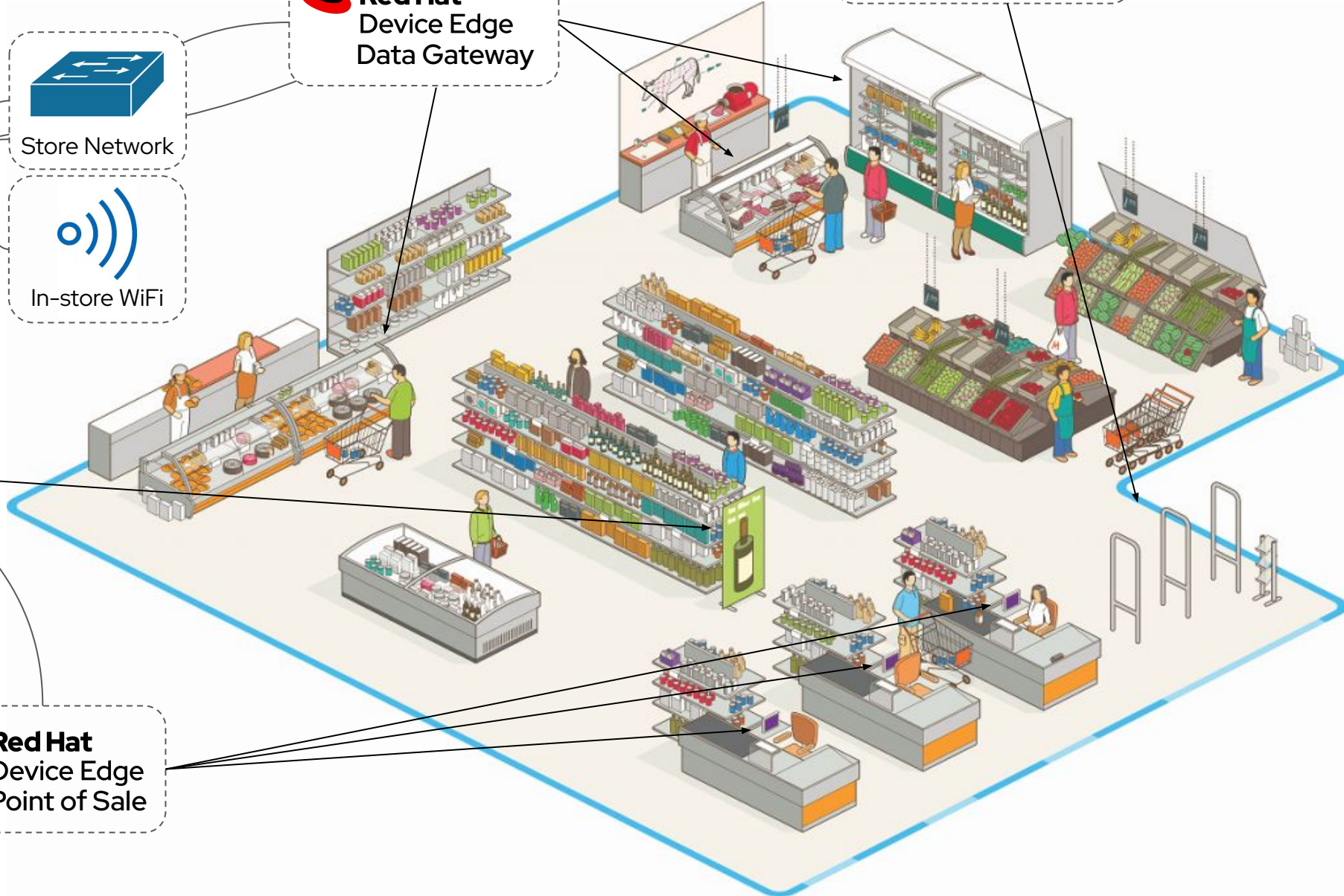


 **Red Hat Device Edge Data Gateway**

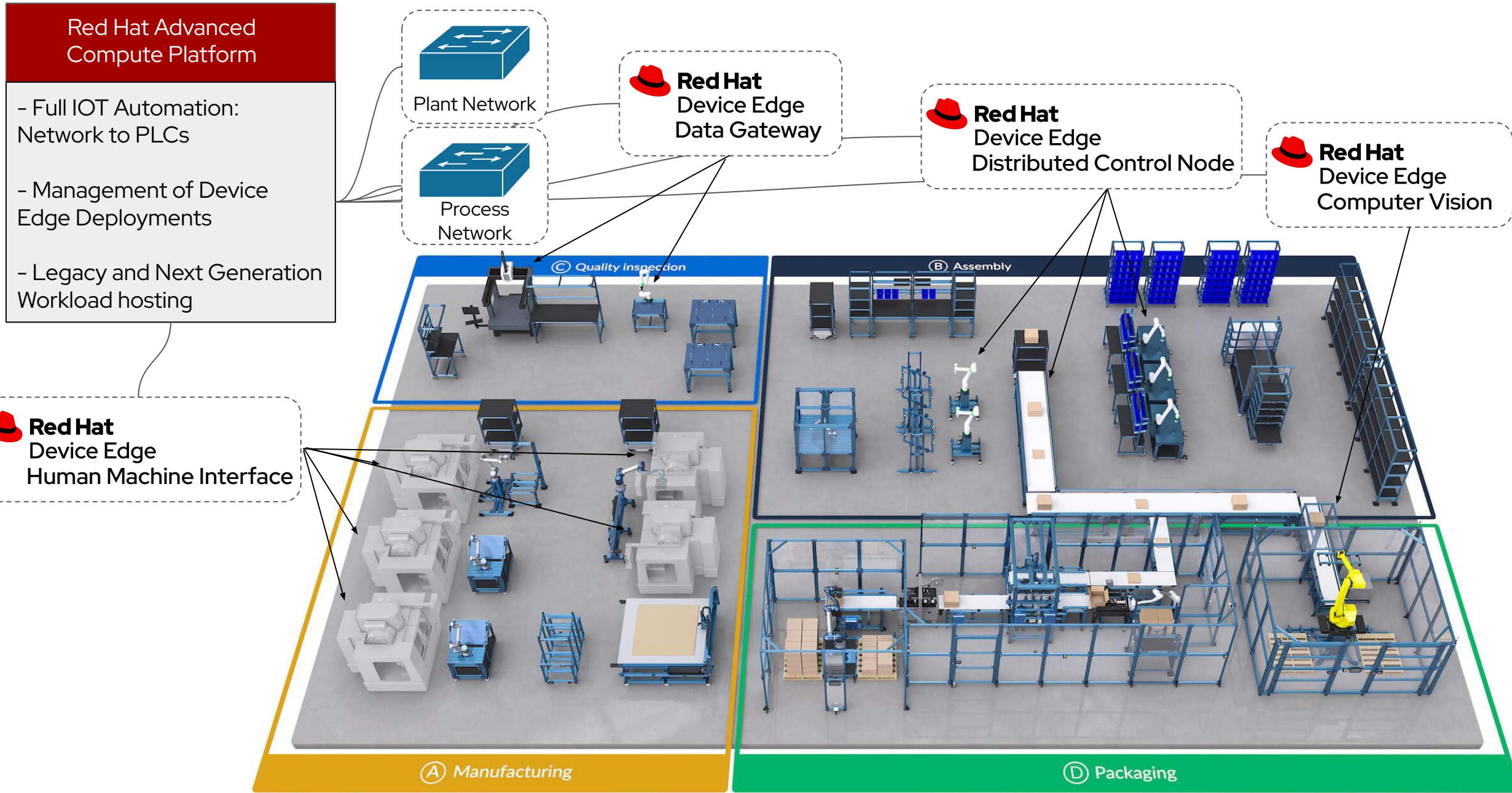
 **Red Hat Device Edge Computer Vision**

 **Red Hat Device Edge Intelligent Display**

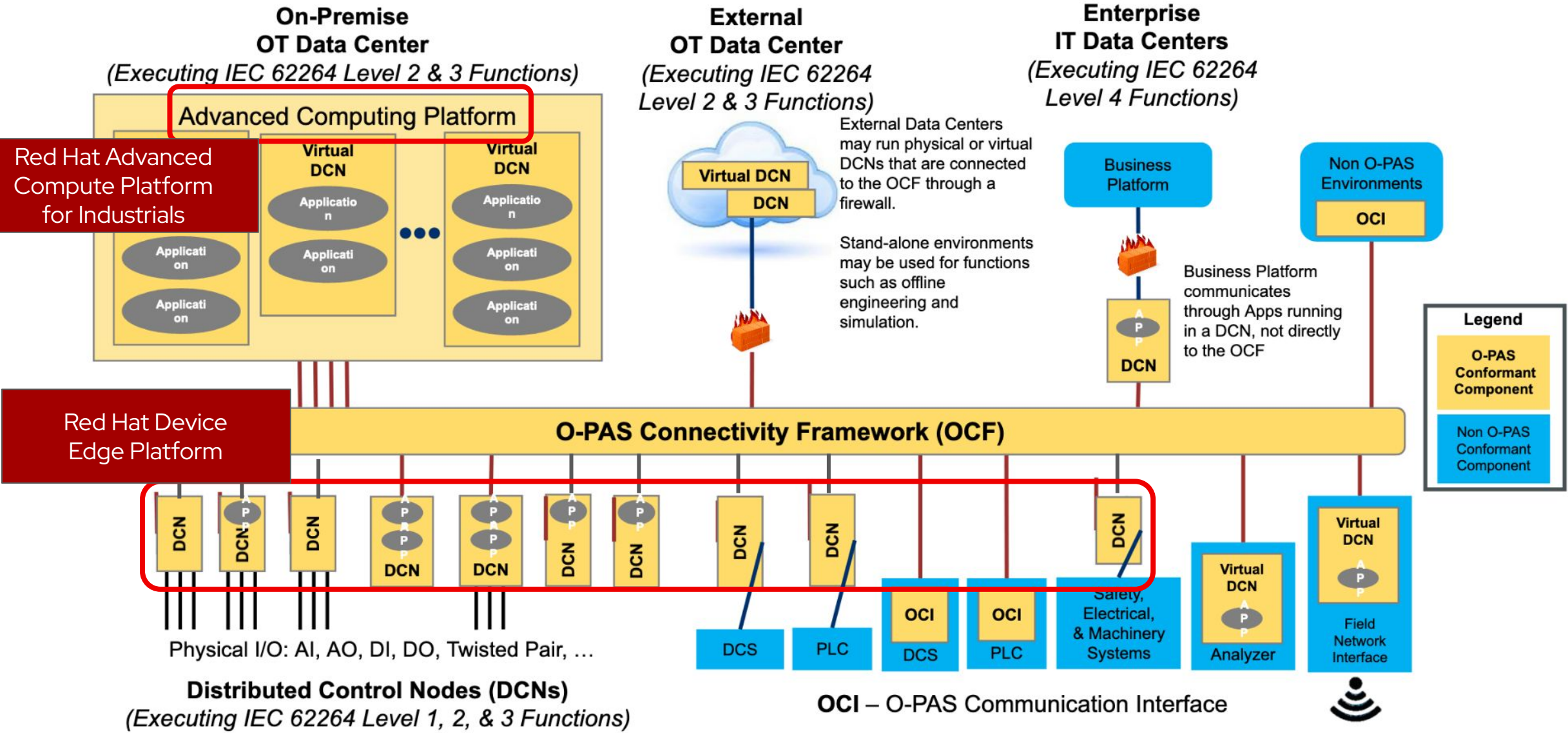
 **Red Hat Device Edge Point of Sale**



One Consistent Platform Across the Industrial Site

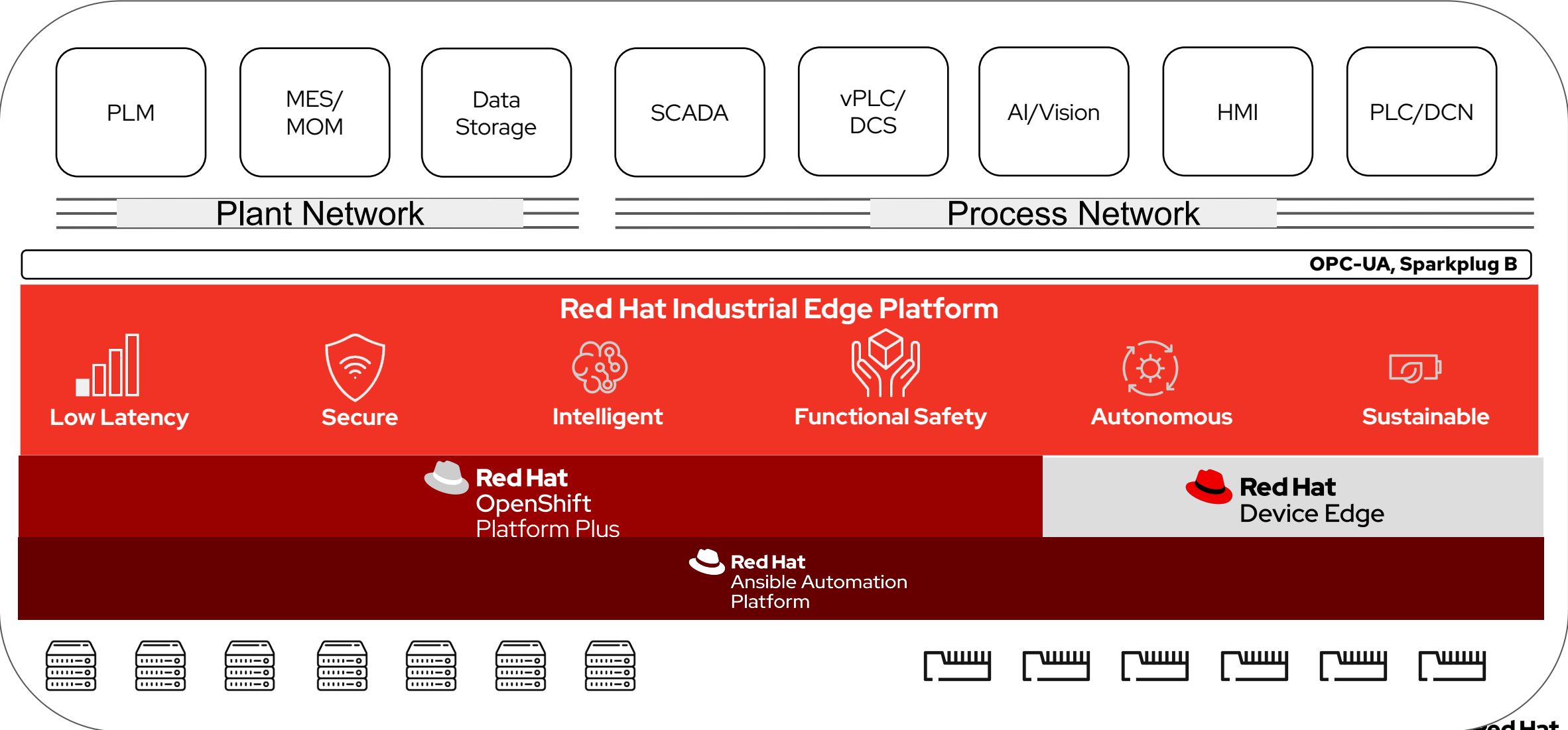


Alignment and Leadership of Industry Direction



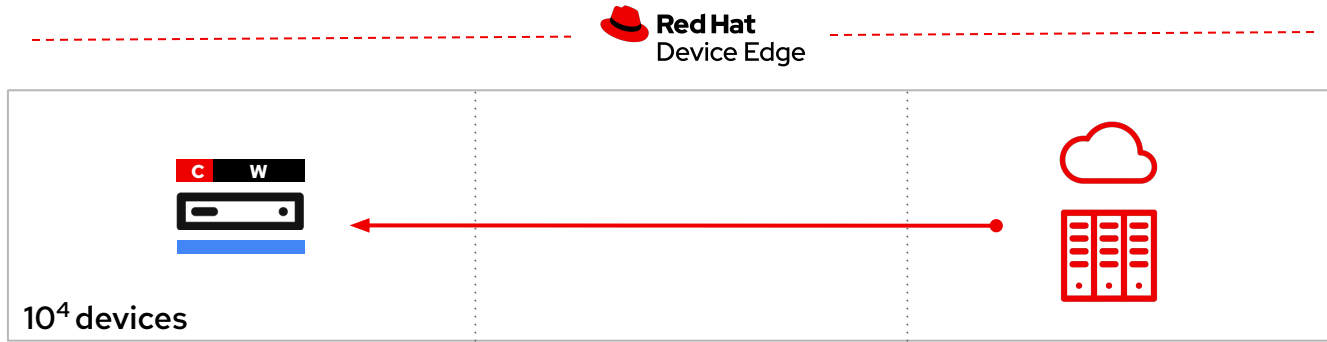
A Next Generation Approach to Industrial Operational Technology

One Open Platform for Deterministic and Non-Deterministic Workloads



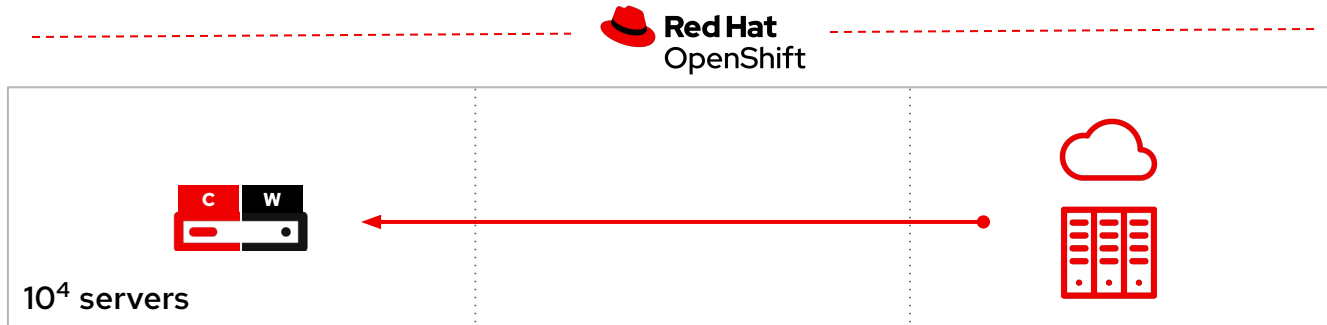
Device Edge platform

Distributed control nodes, limited compute hardware, purpose built systems



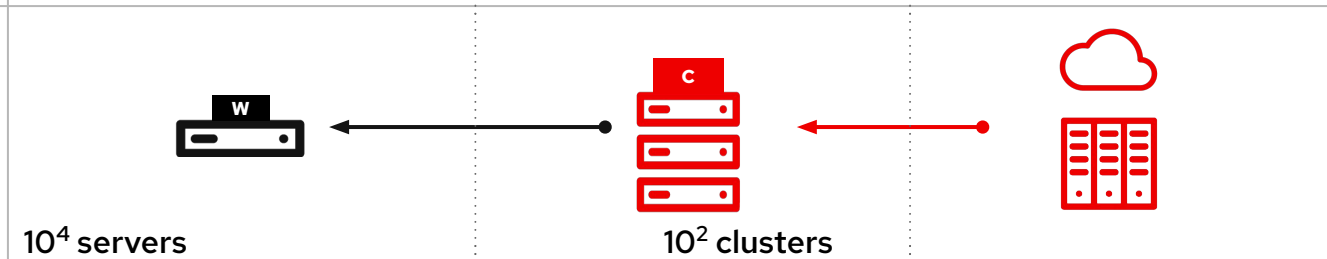
Non-Highly Available ACP

Lower compute, small site deployments



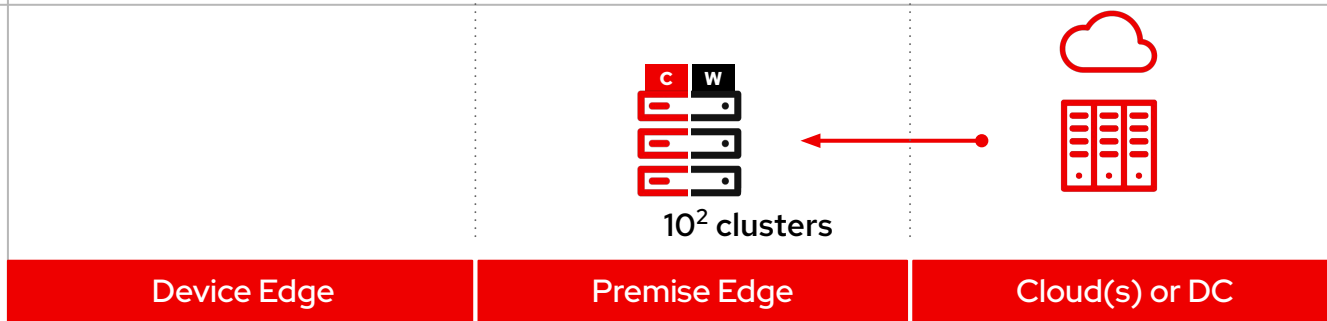
(Remote) worker nodes

Geographically close, no premise edge deployments



Highly Available ACP

Full functionality for autonomous site operations



Minimum System Requirements (per node):

w/o k8s:
1 Core
2 GB RAM

with k8s:
2 Core
2GB RAM

4 Cores
16GB RAM

Worker:
1 Core
8 GB RAM

Control:
2 Core
16GB RAM

4 Cores
16GB RAM

Device Edge

Premise Edge

Cloud(s) or DC

Cluster management and application deployment

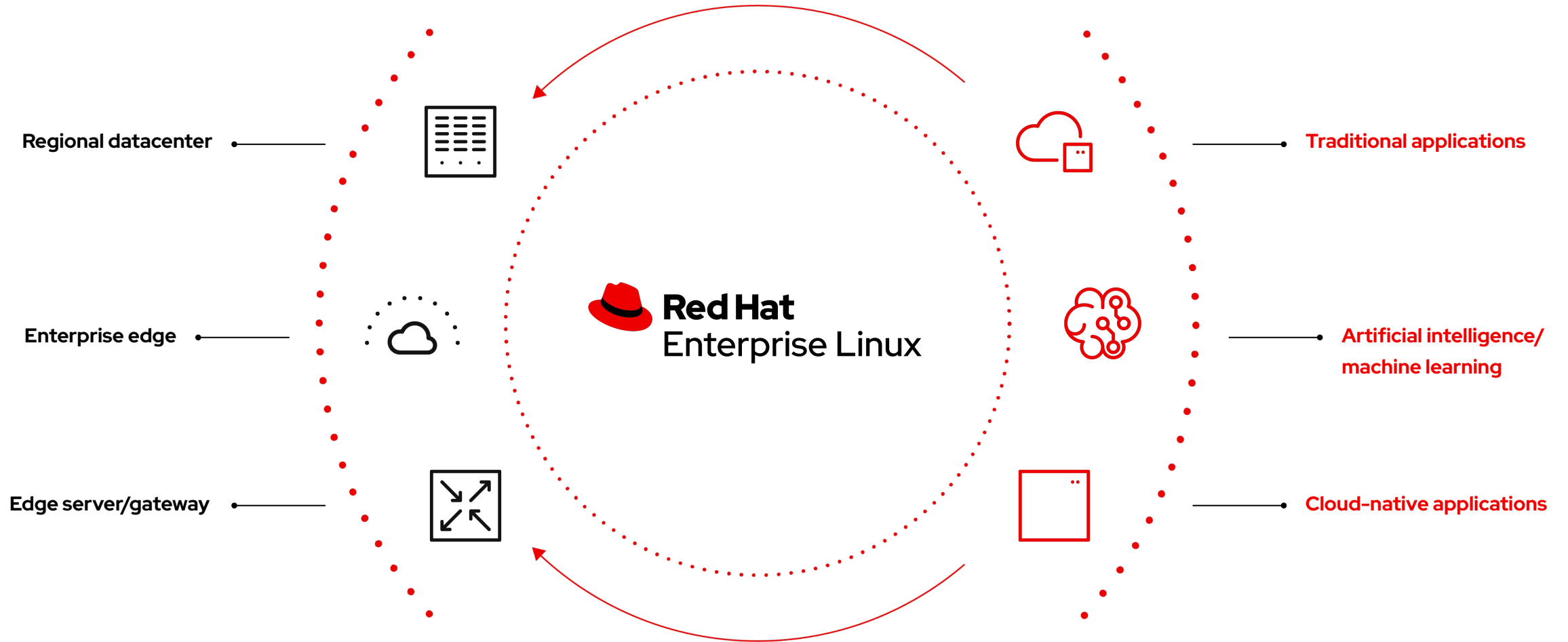
Kubernetes node control

Control node

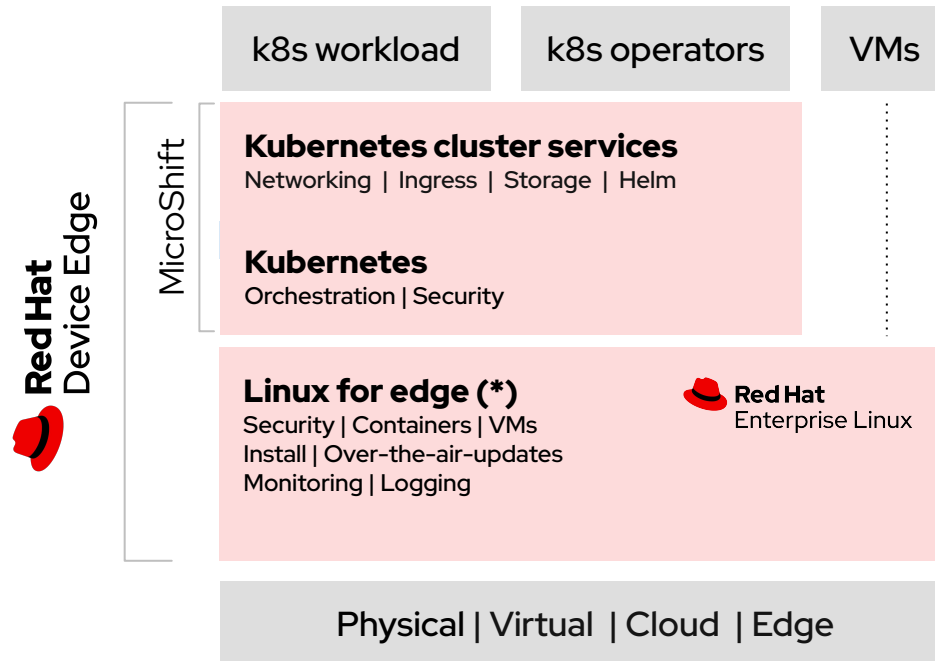
Worker node

Red Hat Device Edge

Flexibility and freedom to run workloads where they're needed

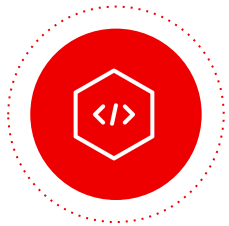


Device Edge Technical Overview



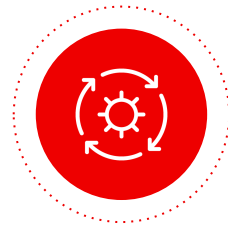
Red Hat Enterprise Linux for Edge

Ensured stability and deployment flexibility



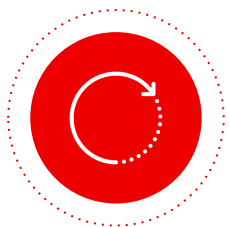
Quick image generation

Easily create purpose-built OS images optimized for the architectural challenges of the edge.



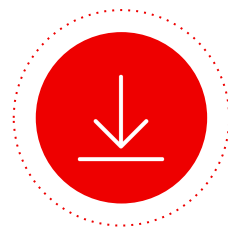
Edge management

Secure and scale with the benefits of zero-touch provisioning, fleet health visibility, and security remediations throughout the entire lifecycle.



Efficient over-the-air updates

Updates transfer significantly less data and are optimized for remote sites with limited or intermittent connectivity.

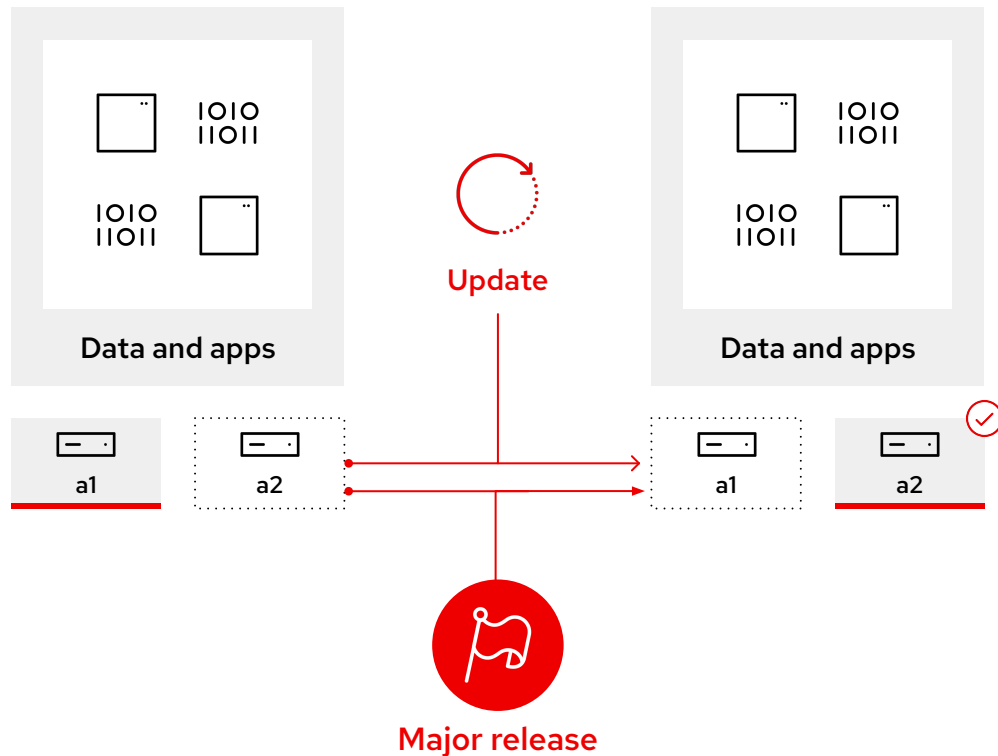


Intelligent rollbacks

Application-specific health checks detect conflicts and automatically reverts to last working OS update, preventing unplanned downtime.

rpm-ostree

Immutable OS and stateful config and storage

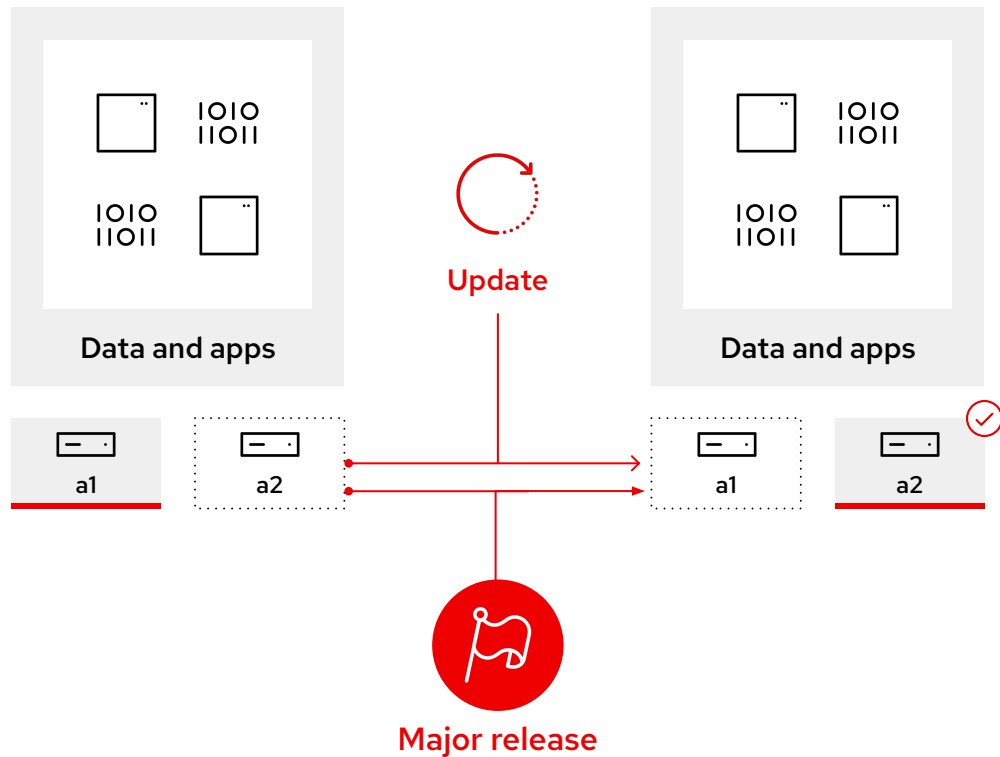


Transactional updates (A → B model)

- ▶ OS binaries and libraries (/usr*) are immutable and read-only.
- ▶ State (r/w) is maintained in /var and /etc.
- ▶ No inbetween state during updates.
- ▶ Updates are staged in the background and applied upon reboot.
- ▶ Reboots can be scheduled with maintenance windows to ensure the highest possible uptime.

rpm-ostree

Immutable OS and stateful config and storage

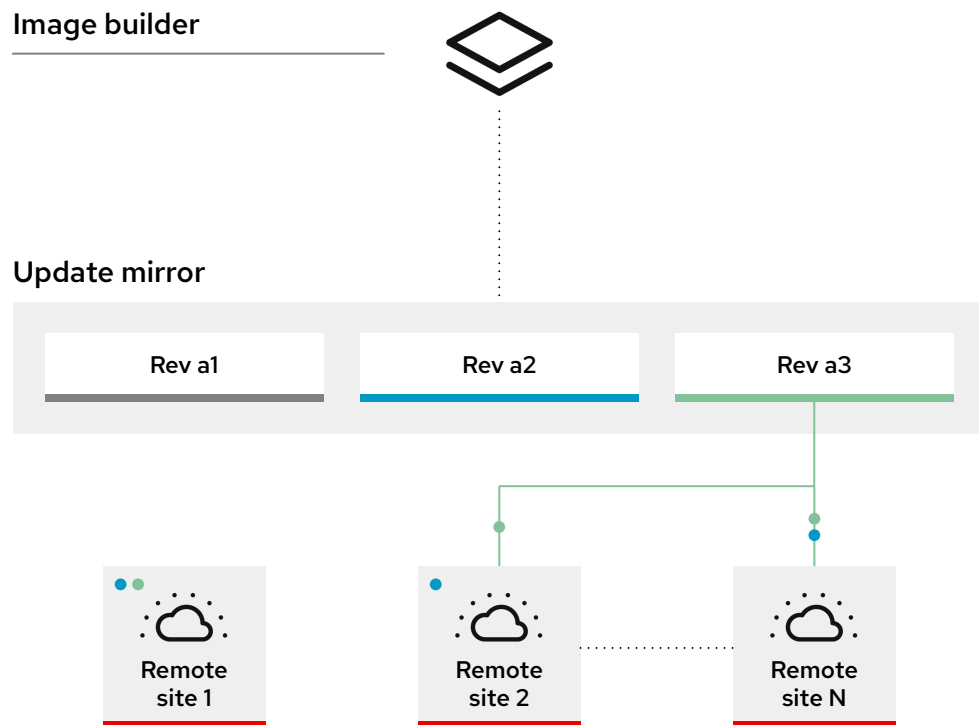


Enables seamless major release upgrades
(Red Hat Enterprise Linux 8→ 9)

- ▶ Help extend the serviceable life of hardware in the field.

Efficient over the air (OTA) OS updates

Easy remote device mirroring: transfer only the deltas



Ideal for disconnected, intermittent, or low-bandwidth (DIL) connections

Transfers significantly less data over the network*

Only transfers updated bits of OS content

Static-deltas can be created to further reduce network usage

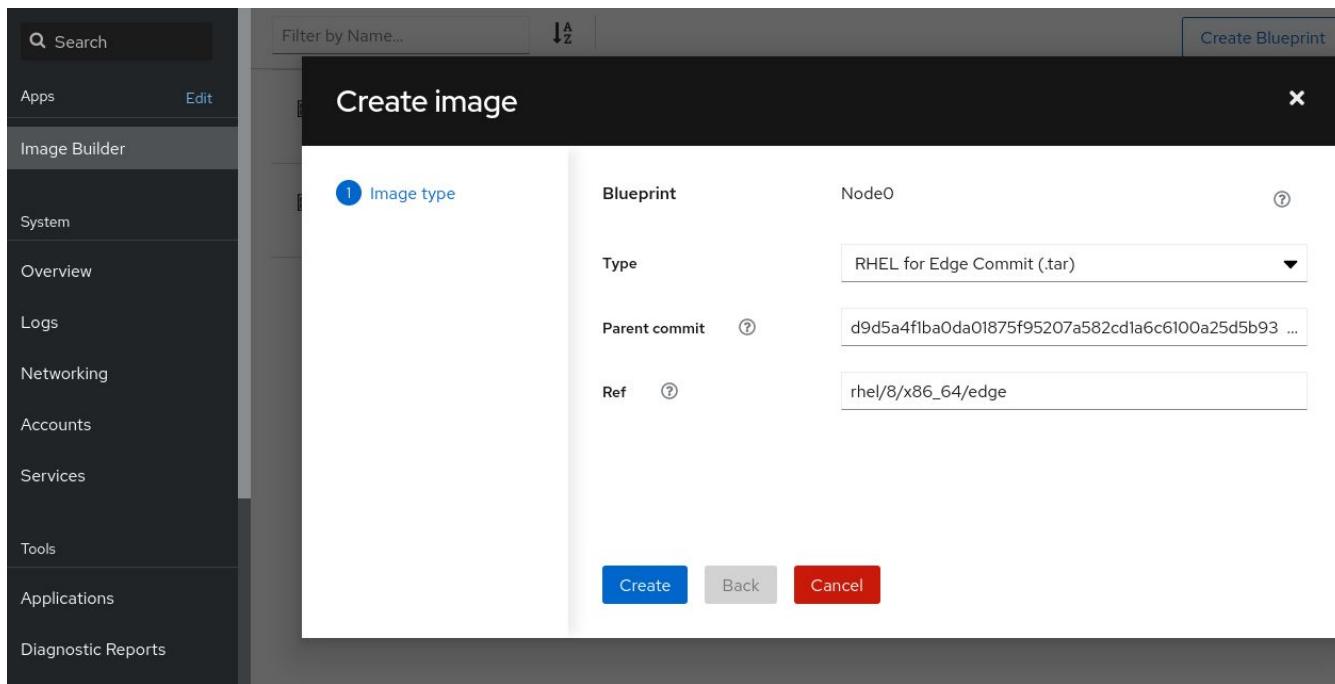
Client initiated connections for firewall-friendly experience

* When compared with traditional appliance image updates or individual package management strategies

Image Builder Overview + Demo

Image builder

Fast image assembly and configuration



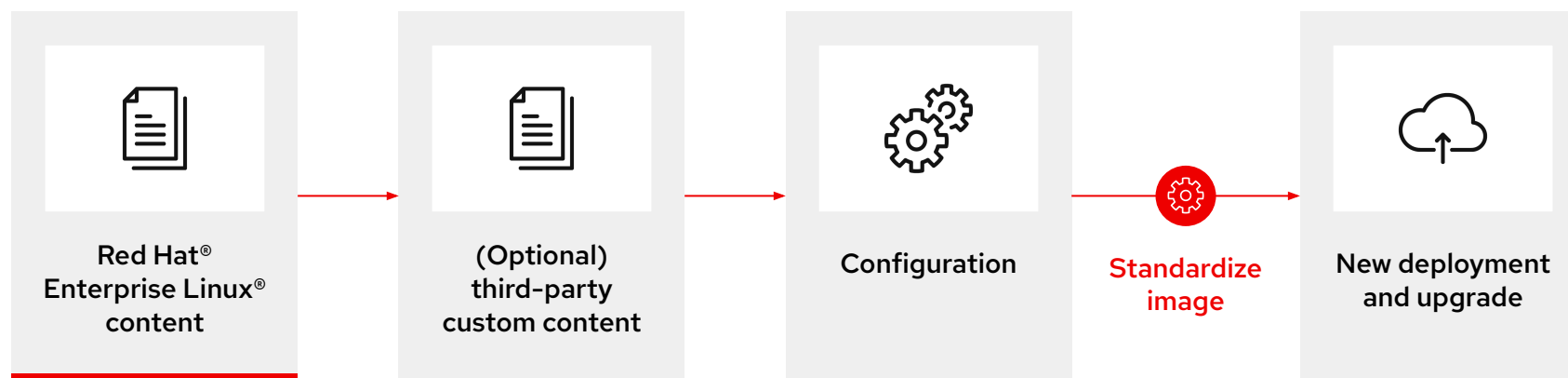
Edge profile generates a small, rpm-ostree image from the latest Red Hat Enterprise Linux 8.3+

OS contents include:

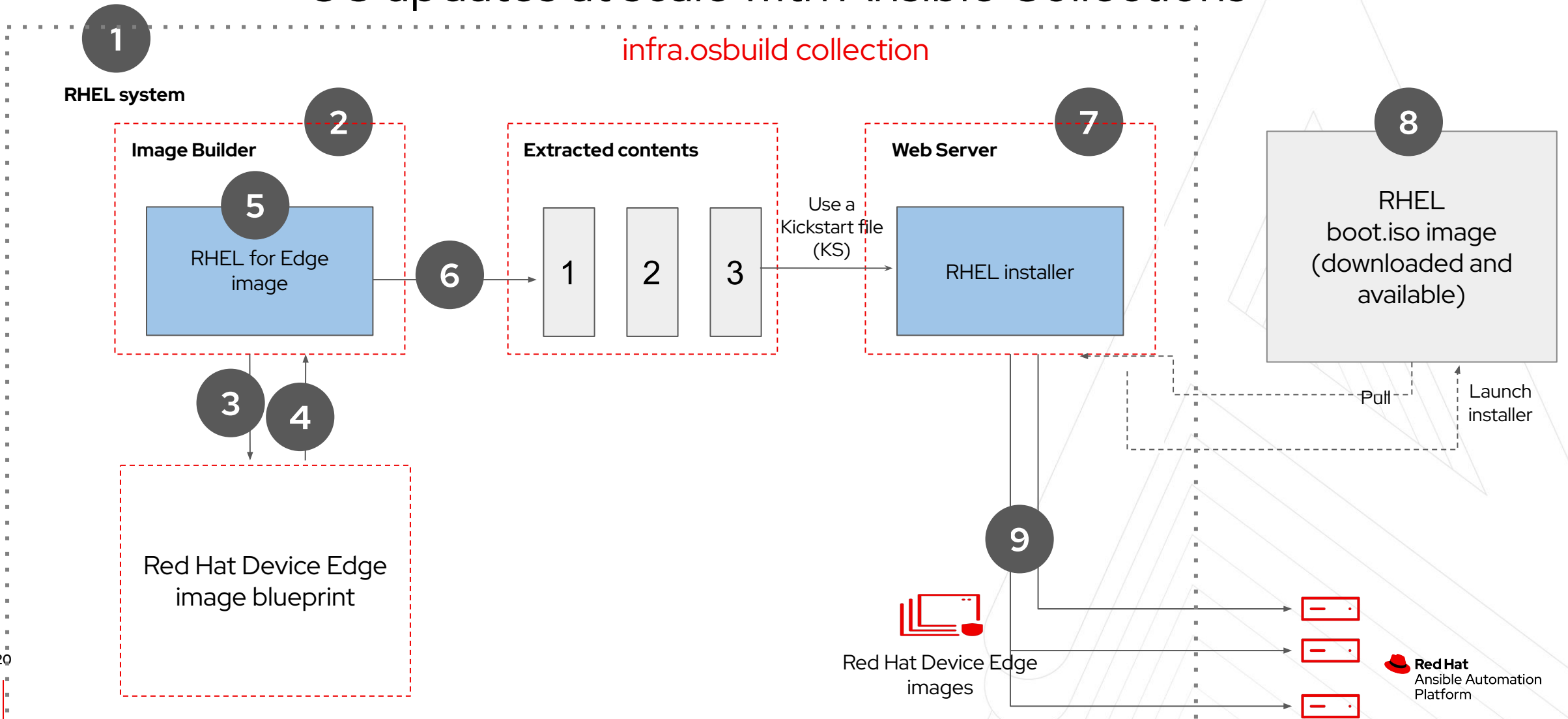
- @core packages (small base install)
- Podman as the container engine
- Additional RPM content (optional)

Image Builder Workflow

Standardize your fleet with image sets to ensure uniform performance



OS updates at scale with Ansible Collections



Deploying microshift containers on top of OS at scale

edge.microshift collection

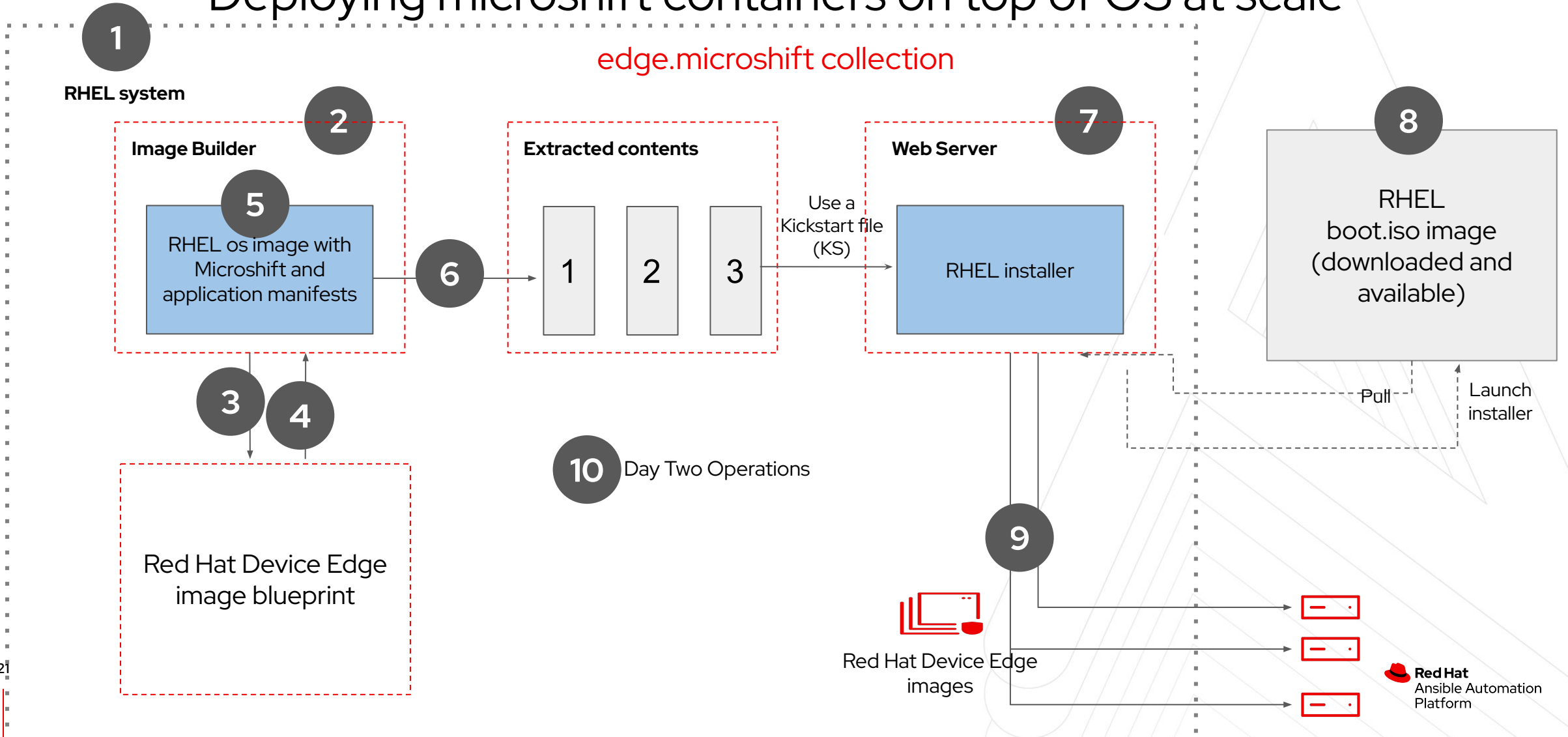


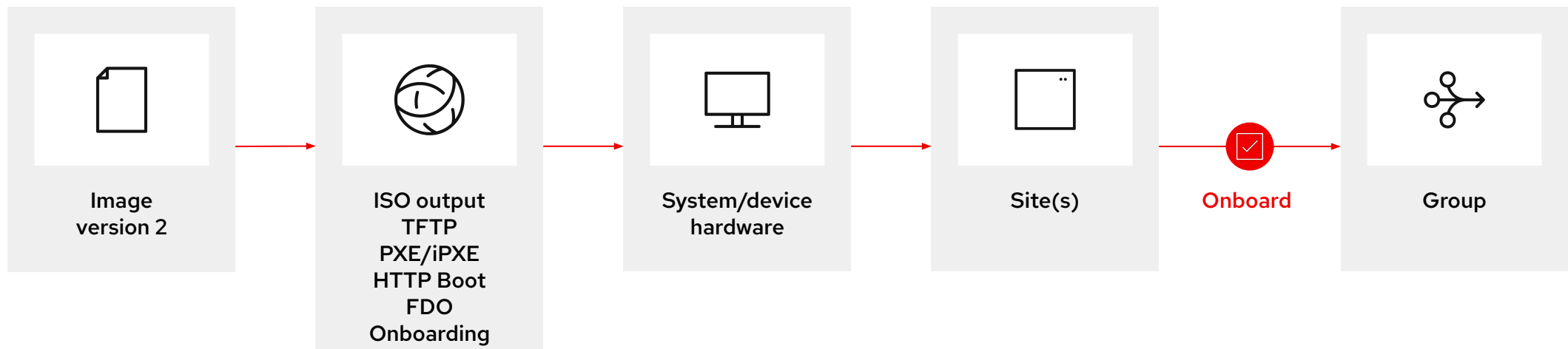
Image Builder Demo

- Image Builder WebUI
- Automating Image Builder with Ansible

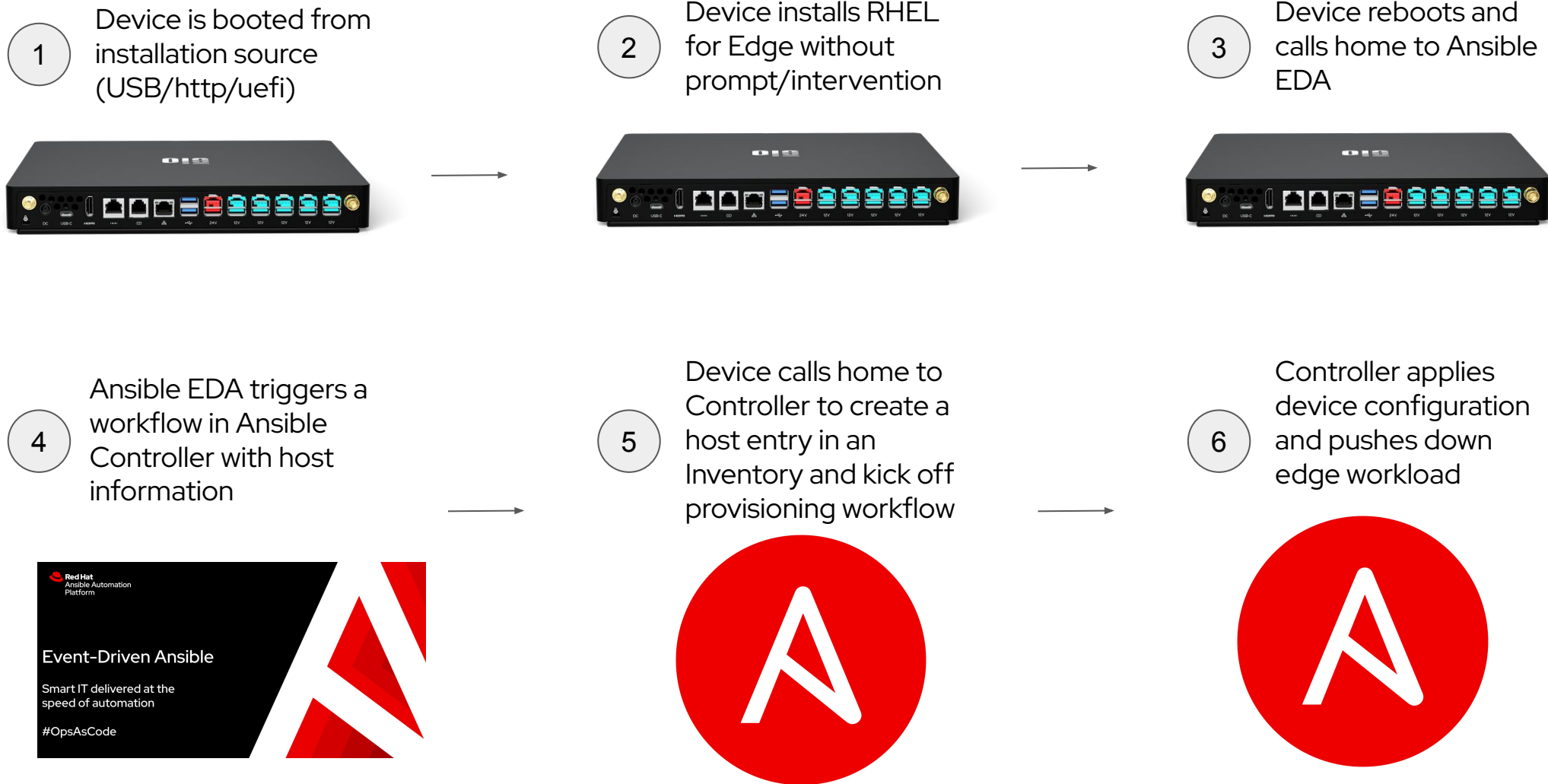
Deploying Red Hat Device Edge

Zero-touch onboarding

Systems onboard automatically at boot and can be sent directly to the site



Initial Install Process and Call Home



Call Home with Minimal Information

Using Systemd to run on next boot:

```
[Unit]
Description=Connect to WiFi
After=network.target
ConditionPathExists=!/var/tmp/wifi-connected

[Service]
Type=oneshot
ExecStartPre=/usr/bin/nmcli radio wifi on
ExecStartPre=/usr/bin/sleep 5
ExecStartPre=/usr/bin/nmcli dev wifi rescan
ExecStartPre=/usr/bin/sleep 5
ExecStartPre=/usr/bin/nmcli dev wifi list
ExecStart=/usr/bin/nmcli dev wifi connect lab-wifi password
'example-password'
ExecStopPost=/usr/bin/touch /var/tmp/wifi-connected
---
[Install]
WantedBy=default.target

[Unit]
Description=Register to Ansible Automation Platform
After=network.target
After=connect-wifi.service
ConditionPathExists=!/var/tmp/aap-registered

[Service]
Type=oneshot
ExecStart=/bin/bash /var/tmp/aap-auto-registration.sh
ExecStopPost=/usr/bin/touch /var/tmp/aap-registered

[Install]
WantedBy=default.target
EOF
```

A simple curl script:

```
#!/bin/bash
IP_ADDRESS=$(nmcli conn show lab-wifi | grep ip address | awk '{print \$4}')
MAC_ADDRESS=$(ip addr | grep wlp -A 1 | grep link | awk '{print \$2}' | sed
's://g')
STUDENT='1'

JSON="{\
  \"ip address\": \"\$IP_ADDRESS\", \
  \"other var\": \"\$OTHER_VAR\", \
  \"mac_address\": \"\$MAC_ADDRESS\" \
}"

/usr/bin/curl -H 'Content-Type: application/json' --data "\$JSON"
https://eda.device-edge.redhat-workshops.com/endpoint
```

Execution Flow:

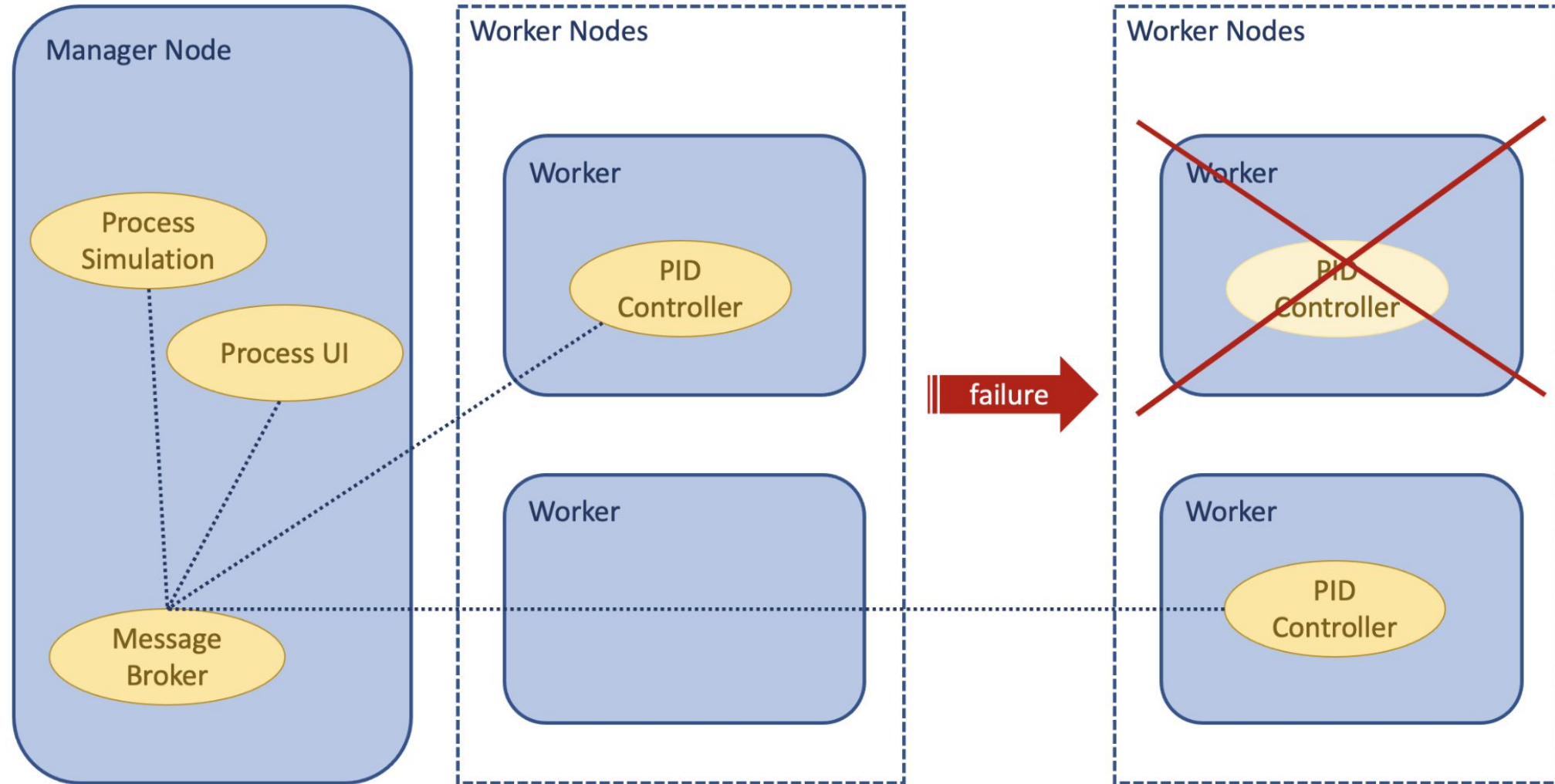
1. System connects to network (WiFi)
2. System collects connection information
3. System calls home to Ansible EDA
4. Ansible EDA calls workflow with system information
5. Device is onboarded

Deploying Red Hat Device Edge Demo

Embedding an Application into an Image

Our Example Process Control Workload

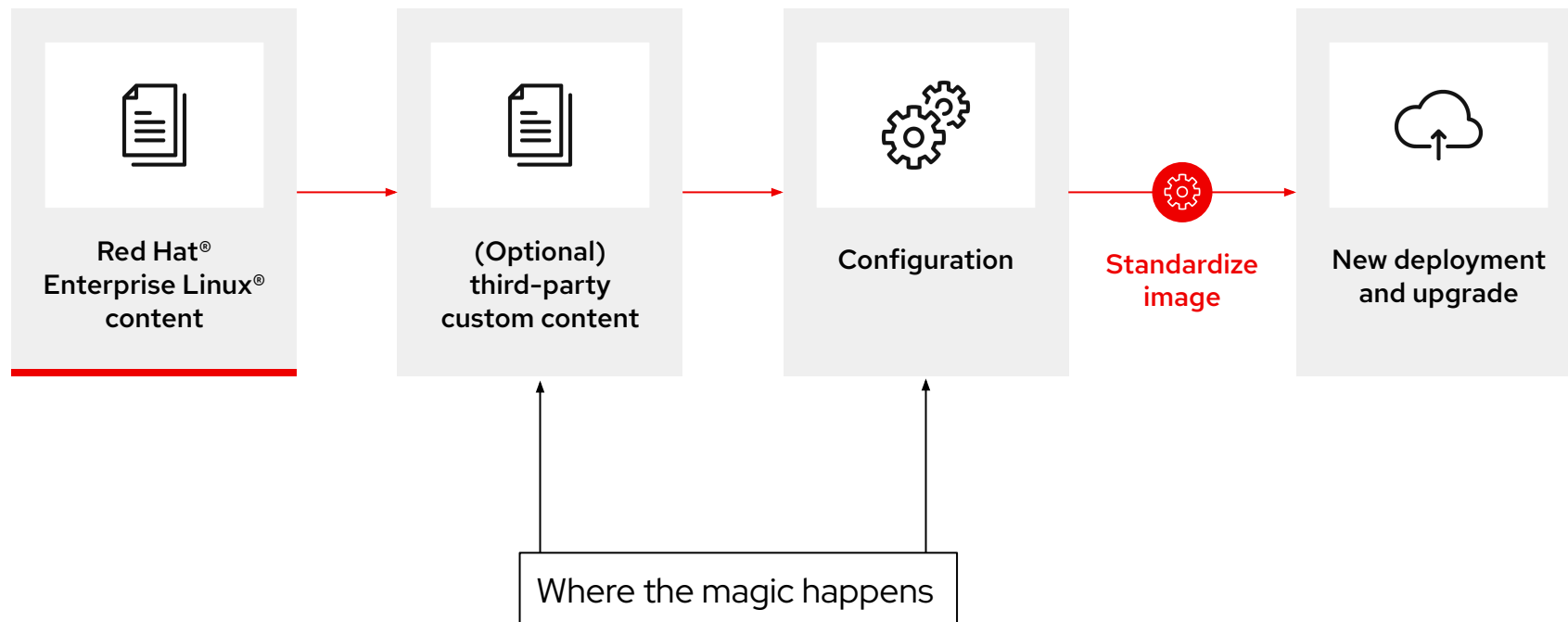
Cloud-native Process Control Demo



Note: Our DCN runs the control plane and worker plane on one system

Image Builder Workflow

Standardize your fleet with image sets to ensure uniform performance



Embedding an Application Examples

[[containers]] is used to specify container images that should be embedded into the image by Image Builder. The images will be available in the default image storage location for the operating system. On RHEL, images will be visible by podman using the `podman images` command.

Note: If 'name' is specified, then the container name will be re-written, otherwise the image name will match the source.

Using the `infra.osbuild` collection:

```
builder compose_containers:
  - name: mqtt
    source: quay.io/device-edge-workshops/process-control-mqtt:1.0.0
  - name: simulate
    source: quay.io/device-edge-workshops/process-control-simulate:1.0.0
  - name: control
    source: quay.io/device-edge-workshops/process-control-control:1.0.0
  - name: ui
    source: quay.io/device-edge-workshops/process-control-ui:1.0.0
```

Directly in toml:

```
[[containers]]
name = "mqtt"
source = "quay.io/device-edge-workshops/process-control-mqtt:1.0.0"

[[containers]]
name = "simulate"
source = "quay.io/device-edge-workshops/process-control-simulate:1.0.0"

[[containers]]
name = "control"
source = "quay.io/device-edge-workshops/process-control-control:1.0.0"

[[containers]]
name = "ui"
source = "quay.io/device-edge-workshops/process-control-ui:1.0.0"
```

Running a Workload with Podman

Kube YAML

```
podman generate kube [UUID]
```

```
apiVersion: v1
kind: Pod
Metadata:
  annotations:
    io.podman.annotations.ulimit:
      nofile=524288:524288
  labels:
    app: thirstywilson-pod
    name: thirstywilson-pod
spec:
  containers:
    - image: ubi9/nginx-120
  command: ["nginx"]
  args: ["-g", "daemon off;"]
  name: thirstywilson
  ports:
    - containerPort: 8080
      hostPort: 8080
  stdin: true
  tty: true
```

systemd unit file

```
podman generate systemd --new [UUID]
```

```
[Unit]
Description= nginx container
After=network-online.target

[Service]

Restart=on-failure
ExecStart=/usr/bin/podman run \
--cidfile=%t/%n.ctr-id \
--cgroups=no-common \
--rm \
--sdnotify=common \
-d \
-p 8080:8080 \
ubi9/nginx-120 nginx -g "daemon off;"

[Install]
WantedBy=multi-user.target
```

Quadlet

```
/etc/containers/systemd/nginx.container
```

```
[Service]
Restart=always

[Container]
ContainerName=nginx
Image=ubi9/nginx-120
PublishPort=8080:8080
Exec=nginx -g "daemon off;"

[Install]
WantedBy=default.target
```


Embedding an Application Examples

Generated quadlet systemd unit file:

```
[Install]
WantedBy=default.target

[Unit]
After=network-online.target
SourcePath=/etc/containers/systemd/process-control.kube
RequiresMountsFor=%t/containers

[X-Kube]
Yaml=/etc/containers/systemd/process-control.yaml
PublishPort=1883:1883

[Service]
KillMode=mixed
Environment=PODMAN_SYSTEMD_UNIT=%n
Type=notify
NotifyAccess=all
SyslogIdentifier=%N
ExecStart=/usr/bin/podman kube play --replace
--service-container=true --log-driver passthrough --publish 1883:1883
/etc/containers/systemd/process-control.yaml
ExecStop=/usr/bin/podman kube down
/etc/containers/systemd/process-control.yaml
```

Note: Quadlet generates files when called at runtime, so generate the files on a test system before embedding them via Image Builder.

kube yaml:

```
---
apiVersion: v1
kind: Pod
metadata:
  name: process-control
spec:
  containers:
    - name: mqtt
      image: docker.io/library/mqtt:latest
    - name: simulate
      image: docker.io/library/simulate:latest
    - name: control
      image: docker.io/library/control:latest
    - name: ui
      image: docker.io/library/ui:latest
  ports:
    - containerPort: 1881
      hostPort: 1881
```

Quadlet kube file:

```
[Install]
WantedBy=default.target

[Unit]
After=network-online.target

[Kube]
Yaml=process-control.yaml # Path to kube yaml
PublishPort=1881:1881 # External ports
```

Embedding an Application Examples

Also ensure target directories are created, services are set to start on boot, and firewall ports are allowed

Directly in toml:

```
[customizations.directories]
path = "/etc/containers/systemd"
mode = "0755"
user = "root"
group = "root"
ensure_parents = false

[customizations.firewall]
ports = "1881:tcp"

[customizations.services]
enabled = ["process-control"]
```

Using the infra.osbuild collection:

```
builder_compose_customizations:
  directories:
    - path: /etc/containers/systemd
      mode: '0755'
      user: root
      group: root
      ensure_parent: 'true'
  firewall:
    ports:
      - '1881:tcp'
  services:
    enabled:
      - process-control
```

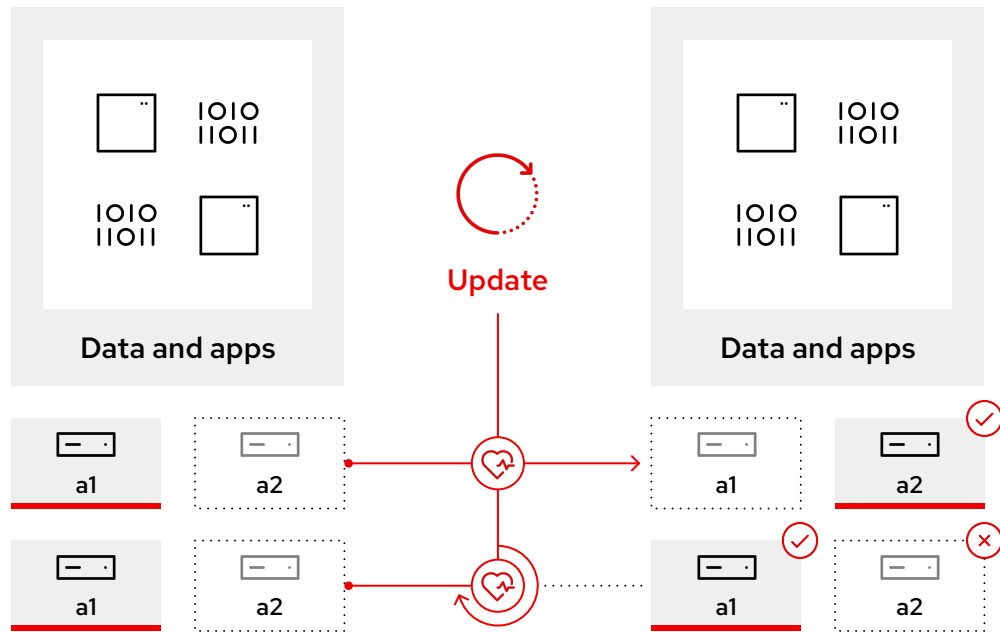
Note: These modifications can be part of an upgraded image, or as part of a new system deployment

Embedding an Application into an Image Demo

Greenboot

Intelligent rollbacks: Greenboot

Additional safeguard for application and OS compatibility

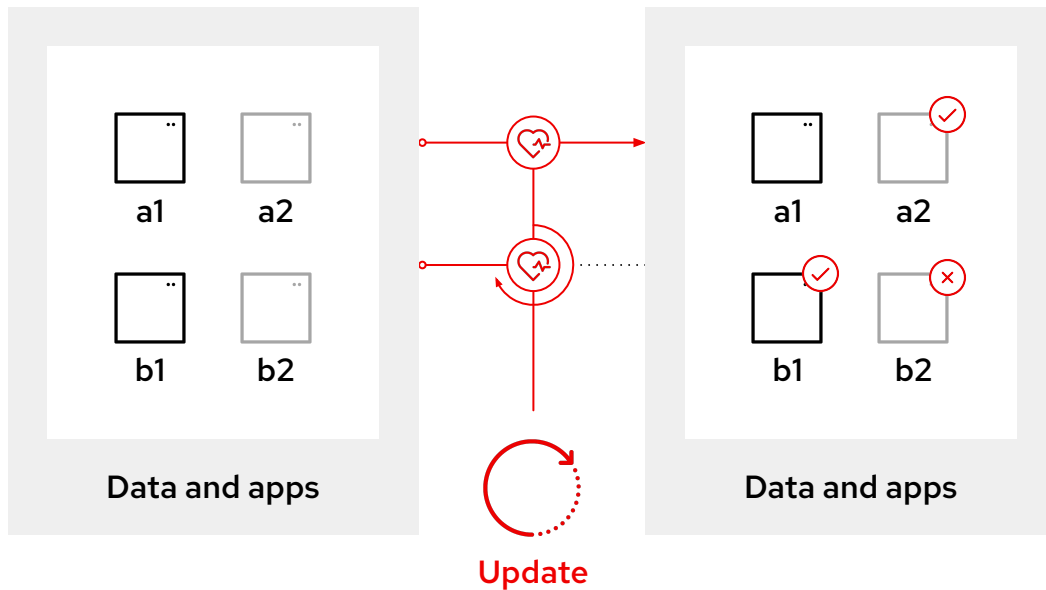


Custom health checks can determine if nodes are functioning properly

- ▶ Health checks are run during the boot process.
- ▶ If checks fail, a counter will track the number of attempts.
- ▶ In a failure state, the node will use rpm-ostree to rollback the update.
- ▶ Examples can include:
 - Basic name resolution
 - Service or container status or health

Intelligent rollbacks: Greenboot

Additional safeguard for application and OS compatibility



Podman will automatically roll back containers if new application versions exit on fail

- Requires use of Podman auto-update
- systemd units are used for managing containers
- **--sdnotify=container** adds the ability to wait and notify when the container's process(s) have started properly
- Podman can generate via:

```
# podman create --name test --label  
io.containers.autoupdate=registry [registry]/[image:tag]  
# podman generate systemd --new test
```

Creating a Greenboot Application Health Check

Using a simple shell script:

```
#!/bin/bash

/usr/bin/sleep 20

RETURN_CODE=$(/usr/bin/curl -s -o /dev/null -w '%{http_code}'
http://localhost:1881)

if [ $RETURN_CODE = '200' ]; then
    exit 0;
else
    exit 1;
fi
```

Now embed in image via file route:

```
builder_compose_customizations:
  files:
    - path: /etc/greenboot/check/required.d/application-check.sh
      mode: '0755'
      user: root
      group: root
      data: "#!/bin/bash\n\n/usr/bin/sleep 20\n\nRETURN_CODE=$(/usr/bin/curl -s
-o /dev/null -w '%{http code}' http://localhost:1881)\n\nif [ $RETURN_CODE =
'200' ]; then\n    exit 0;\nelse\n    exit 1;\nfi"
```

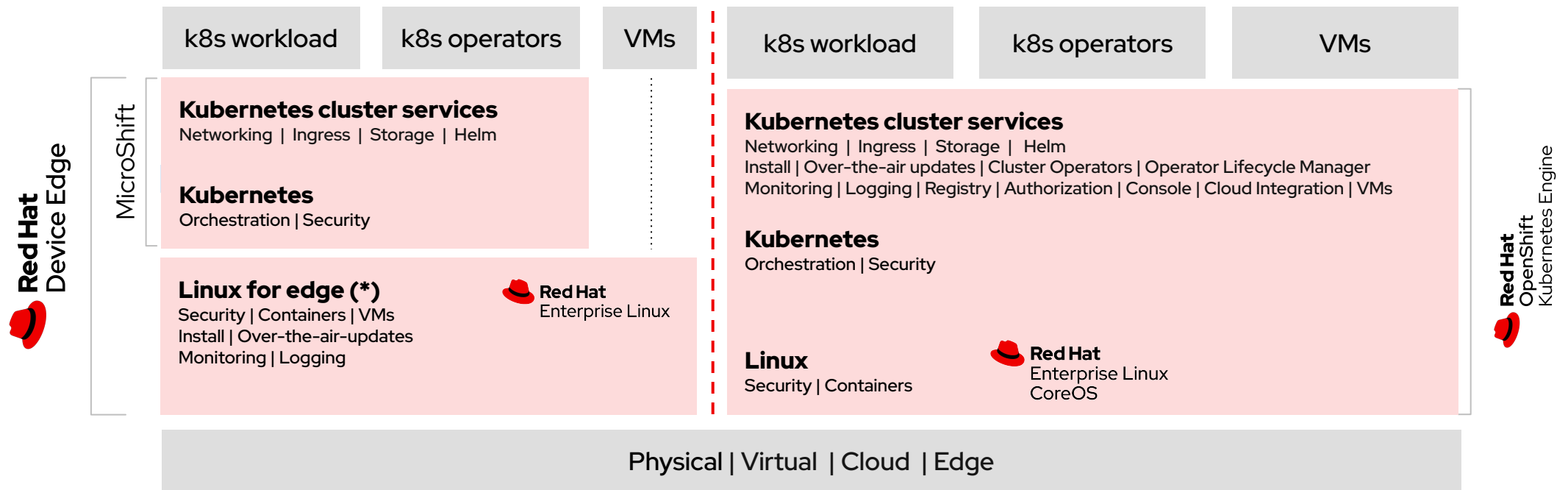
Tip: Use `sed -E ':a;N;$!ba;s/\r{0,1}\n/\n/g'` to convert files into a single line with proper newlines embedded

- **/etc/greenboot/check/required.d** contains the health checks that must not fail (if they do, GreenBoot will initiate a rollback)
- **/etc/greenboot/check/wanted.d** contains health scripts that may fail. GreenBoot will log that the script failed, however, it will not rollback.
- **/etc/greenboot/green.d** contains scripts that should be run after GreenBoot has declared the boot successful
- **/etc/greenboot/red.d** contains scripts that should be run after GreenBoot has declared the boot as failed.

Greenboot Demo

Deploying Microshift to Run an Embedded Application

Device Edge with MicroShift compared to Openshift



* recommended for edge deployments: [Red Hat Enterprise Linux for Edge Images](#), rpm-ostree, immutable, atomic upgrade, over the air flavour of Red Hat Enterprise Linux.

Adding Microshift to a Red Hat Device Edge Image

The infra.osbuild collection automatically manages repositories (sources) for Image Builder

Adding repositories:

```
builder_rhsm_repos:  
- "rhocp-4.13-for-rhel-9-x86_64-rpms"  
- "fast-datapath-for-rhel-9-x86_64-rpms"
```

Adding packages:

```
builder_compose_packages:  
- microshift  
- microshift-greenboot
```

Adding customizations:

```
builder_compose_customization:  
  firewall:  
    ports:  
      - '6443:tcp'  
      - '1881:tcp'  
  services:  
    enabled:  
      - microshift  
      - deploy-pull-secret
```

These additions get the base platform of Microshift built into the image

Note: Microshift can be added or removed through normal rpm-ostree updates

Giving our Embedded Application to Microshift to Run

Microshift will read /etc/microshift/manifests looking for applications to deploy

kustomization:

```
---
apiVersion: kustomize.config.k8s.io/v1beta1
kind: Kustomization
namespace: process-control
resources:
  - process-control.yaml
```

kustomization.yaml has my application
yaml
listed under **resources**.

Namespace and services:

```
---
apiVersion: v1
kind: Namespace
metadata:
  name: process-control
---
apiVersion: v1
kind: Service
metadata:
  name: mqtt
spec:
  ports:
    - port: 1883
      protocol: TCP
      targetPort: 1883
  selector:
    app: mqtt
  type: NodePort
---
apiVersion: v1
kind: Service
metadata:
  name: ui
spec:
  ports:
    - port: 1881
      protocol: TCP
      targetPort: 1881
  selector:
    app: ui
  type: NodePort
```

Deployments:

```
---
apiVersion: apps/v1
kind: Deployment
metadata:
  name: mqtt-deployment
spec:
  selector:
    matchLabels:
      app: mqtt
  replicas: 1
  template:
    metadata:
      labels:
        app: mqtt
    spec:
      containers:
        - name: mqtt
          image:
            quay.io/device-edge-workshops/process-control-mqt
            t:1.0.0
          ports:
            - containerPort: 1883
              name: mqtt-port
```

Deploying Microshift to Run an Embedded Application Demo

Thank you

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